

Front propagation in a transport model with a nonlocal nonlinear condition at the boundary

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Joint work with G. Faye and M. Zhang

Unknown function: $u(t, x, i); t > 0, i > 0, x \in \mathbb{R}$

$$\begin{cases} \partial_t u + \partial_i u = -\gamma(i)u & (t > 0, x \in \mathbb{R}, i > 0) \\ u(t, x, 0) = f \left[\int_0^{+\infty} \beta(i) K *_x u(t, \cdot, i) di \right]. \\ u(0, x, i) = u_0(x, i) \text{ compactly supported in } (x, i) \end{cases}$$

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- $f(0) = 0; f(u) > 0, f''(u) < 0$ for $u > 0$.
- $K(x) \geq 0, C^\infty$, even, compact support, unit mass.
- $\beta(i) \geq 0, \gamma(i) > 0$, both C^∞ w. compact support.

Sharp asymptotic behaviour $t \rightarrow +\infty$?

Motivations

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Outline

- The Fisher-KPP equation
- Derivation of the model
- What to expect, known results
- Sharp asymptotic behaviour

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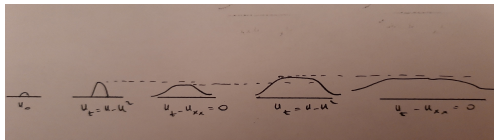


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Invasion of whole line by the state $u = 1$.

Invasion by state $u = 1$: mathematical description

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Epidemiological relevance questionable, but interesting mathematical issues

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Modelling of spread of an epidemic needs, at the very least:

- A contamination mechanism
- A diffusion process.

Contamination: Kermack-McKendrick model (1927)



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 - Update of susceptibles: $\dot{S} = -\mathcal{I}(t, 0)$.

At $t = 0$, injection of small amount of infected $I_0(i)$.

β and γ constant: SIR model

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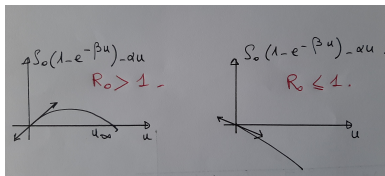
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Define $R_0 = S_0\beta/\gamma$.



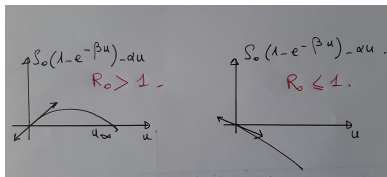
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- $R_0 \leq 1$: $u(t) \rightarrow u_\infty(I_0)$ small (extinction).
- $R_0 > 1$: $u(t) \rightarrow u_\infty(I_0) > u_\infty$. Susceptibles $\rightarrow S_0 e^{-\beta u_\infty(I_0)}$.

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Remark. Def. of R_0 consistent w. β and γ constant.

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- Fisher-KPP type structure: linearised equation. around 0

$$v_t + S_0\beta(v - K * v) = \gamma(R_0 - 1)v.$$

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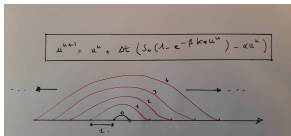
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From then on we will consider the Cauchy Problem, without RHS $\mathcal{I}(0, x, i)$.

What to expect, known results

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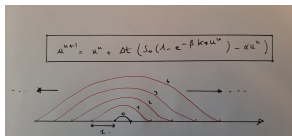
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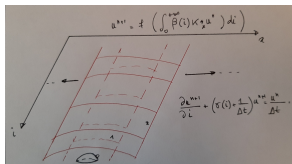
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Nonlocal transport model



$$\lim_{t \rightarrow +\infty} u(t, x, i) = u_\infty(i), \quad \text{steady solution of Kermack-McKendrick.}$$

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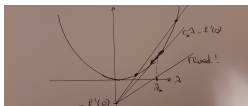
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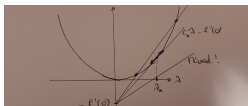


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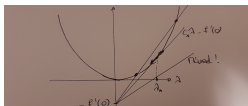
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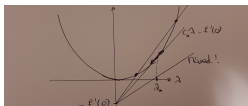
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Theorem (R., 2023). There is x_∞ such that

$$X(t) = c_*t - \frac{3}{2\lambda_*} \ln t + x_\infty + o(t).$$

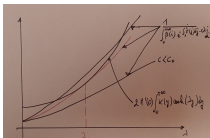
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Nonlocal transport model: known results

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$$\begin{cases} \partial_t u + \partial_i u = -\gamma(i)u & (t > 0, x \in \mathbb{R}, i > 0) \\ u(t, x, 0) = f'(0) \int_0^{+\infty} \beta(i) K *_{x} u(t, \cdot, i) di. \end{cases}$$
with $u(t, x, i) = e^{-\lambda(x-ct)} u(i)$.

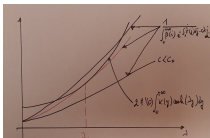


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$X(t)$: furthest point x to the right s.t. $u(t, x, 0) = u_\infty/2$.

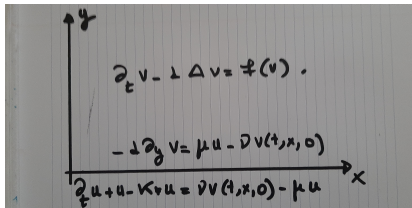
Sharp asymptotic behaviour

Theorem (Faye, Zhang, R. 2024). $X(t) = c_* t - \frac{3}{2\lambda_*} \ln t + O(1)$.

The result

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Starting point: Analogy with "Road-field model" (Berestycki, Rossi, R.)



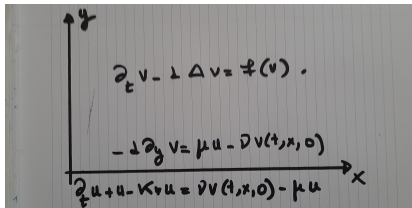
A photograph of a hand-drawn diagram on a grid background. It shows a coordinate system with a vertical y-axis and a horizontal x-axis. Three partial differential equations are written in the space:

$$\partial_t v - \Delta v = f(v),$$
$$-\Delta_y v = \mu u - \mathcal{D}v(t, x, 0)$$
$$\partial_t u + u - \kappa v u = \mathcal{D}v(t, x, 0) - \mu u$$

The result

Theorem (Faye, Zhang, R. 2024). $X(t) = c_* t - \frac{3}{2\lambda_*} \ln t + O(1)$.

Starting point: Analogy with "Road-field model" (Berestycki, Rossi, R.)



A photograph of a hand-drawn diagram on a coordinate system. The vertical axis is labeled 'y' and the horizontal axis is labeled 'x'. The origin is marked with a small '0'. Three equations are written in black ink:

$$\partial_t v - \lambda \Delta v = f(v),$$
$$-\lambda \partial_y v = \mu u - \partial V(t, x, 0)$$
$$\partial_t u + u - \kappa \nabla u = \partial V(t, x, 0) - \mu u$$

- **Idea:** view model as a road-field model instead of integral equation.
- **Common point:** global dynamics directed by line $\{y = 0\}$.
- **Main advantage:** flexibility with Cauchy Problems.
- **Main difference:** Boundary condition NOT an evolution equation.

Ingredients of proof

— Comparison principles

- In the whole domain
- In domains of the form $x \geq X(t, i)$ or $x \leq X(t, i)$.

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$$u(t, x, i) \approx \frac{e^{-\lambda_*(x - c_*(t-i))}}{t - i} G_*\left(\frac{x - c_*(t - i)}{\sqrt{t - i}}\right), \quad G_*(\xi) = \xi e^{-\xi^2/d_*}$$

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— Travelling waves: sol. of form $\phi(x - ct, i)$.

Existence iff $c \geq c_*$. Also, $\phi_{c_*}(x, i) \underset{x \rightarrow +\infty}{\sim} \pi_*(i) x e^{-\lambda_* x}$.

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$$\sigma(t) \approx \frac{3}{2\lambda_*} \ln t + O(1).$$

- $u(t, x, i)$ falls eventually between two translates of

$$\phi_{c_*}\left(x - c_*t - \frac{3}{2\lambda_*} \ln t\right)$$

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Work in progress

- Location of $X(t)$ with precision $o_{t \rightarrow +\infty}(1)$,
- original Kermack-McKendrick model and study of $\mathcal{I}(t, x, i)$.

Thank you!